# Aka Time Code

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# ΤНΕ CARLC ROVNew York Times-bestselling author of Seven Brief Lessons on Physics

**The difference between things and** events is that things persist in time; events have a limited duration. A stone is a prototypical "thing": we can ask ourselves where it will be tomorrow. Conversely, a kiss is an "event." It makes no sense to ask where the kiss will be tomorrow. The world is made up of a network of kisses, not of stones.'



'On closer inspection, even the things that are most "thinglike" are nothing more than long events. The hardest stone . . . is in reality a complex vibration of quantum fields, a momentary interaction of forces, a process that for a brief moment [eons] manages to keep its shape.'





**On closer inspection, even the things that are most** "thinglike" are nothing more than long events. The hardest stone, in the light of what we have learned from chemistry, physics, from mineralogy, from geology, from psychology, is in reality a complex vibration of quantum fields, a momentary interaction of forces, a process that for a brief moment [eons] manages to keep its shape, to hold itself in equilibrium before disintegrating into dust, a brief chapter in the history of interactions between the elements of the planet, a trace of Neolithic humanity, a weapon used by a gang of kids, an example in a book about time, a metaphor for an ontology, a part of a segmentation of the world that depends more on how our bodies are structured to perceive than on the object of perception – and, gradually, an intricate knot in that cosmis game of mirrors that constitutes reality. The world is not so much made up of stones as of fleeting sounds, or of waves moving through the sea.















More situated in time than linear media or static artifacts Temporal and meta-temporal medium

# CODE MUSIC

Situated in time, with loops and branches, but not self-referential

4 <b>4</b>	







### **1/4 REST**

# 

Symbols for structuring execution

### LOOP DELIMITER SYMBOL



### **REPEAT FIRST SECTION ONCE**

REPEAT SECOND SECTION, USE ALTERNATE ENDING SECOND TIME



Simple outline can be decoded in sophisticated way by specially-trained agents aka 'musicians'











### https://www.reedmaxson.com/graphic-scores.html



\*) flageolet tones



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Rite of Spring Score, Igor Stravinsky



La Cachucha, by Friedrich Albert Zorn (wikipedia)

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Score of Ice Spirits, Meredith Monk

![](_page_19_Picture_0.jpeg)

# These things can make music, but neither of them is music

![](_page_20_Picture_0.jpeg)

More situated in time than linear media or static artifacts

![](_page_20_Figure_2.jpeg)

# BRANCH

![](_page_21_Picture_0.jpeg)

### Refer to and alter source

![](_page_21_Picture_2.jpeg)

![](_page_22_Picture_0.jpeg)

berg LP [US] bloomberg.com/graphics/2015-paul-ford-what-is-code/

# Let's Be

A computer is a clock with benefits. They all work the sa one step at a time: Tick, take a number and put it in box put it in box two. Tick, operate (an operation might be a two numbers and put the resulting number in box one. and if it is, go to some other box and follow a new set of

![](_page_22_Figure_4.jpeg)

"A computer is a clock with benefits. They all work the same, doing secondgrade math, one step at a time: Tick, take a number and put it in box one. Tick, take another number, put it in box two. Tick, *operate* (an operation might be addition or subtraction) on those two numbers and put the resulting number in box one. Tick, check if the result is zero, and if it is, go to some other box and follow a new set of instructions."

![](_page_22_Picture_7.jpeg)

![](_page_23_Picture_0.jpeg)

![](_page_24_Picture_0.jpeg)

![](_page_24_Picture_1.jpeg)

![](_page_25_Picture_0.jpeg)

### **Xiomi Watch 26Mhz Oscillator** (probably) iFixIt

1 ....

-

11

100

400 U U 0 000 vit

NUM NUM BUCK.

0 0

1010

101

![](_page_26_Picture_0.jpeg)

- LVPECL Differential Output
- Operating Range: 2.5 V ±5%, 3.3 V ±10%

![](_page_26_Picture_9.jpeg)

![](_page_26_Picture_12.jpeg)

XXX.XXXX = Output Frequency (MHz) = Assembly Location

### **ONSEMI A037L 707.35MHZ VCX0**

![](_page_27_Picture_0.jpeg)

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381	this.redr	aw();		

![](_page_28_Figure_1.jpeg)

# EASING

# SIMULATION

Use physics or other rules to determine next frame for one or more objects.

# TIMELINES

Schedule code for execution in the future

### Smoothly transition a variable from one value to another in a set time

![](_page_30_Picture_0.jpeg)

## ROBERT PFNNFR

### Quadratic Easing

Flash's Timeline tweens use something called quadratic easing—which could actually be termed "normal" easing. The word quadratic refers to the fact that the equation for this motion is based on a squared variable, in this case,  $t^2$ :

 $p(t) = t^2$ 

![](_page_31_Picture_5.jpeg)

NOTE: I always wondered why the term quad-ratic (the prefix means "four") is used to describe equations with a degree of two  $(x^2)$ . While writing this chapter, I finally looked it up in the dictionary (RTFD, you might say). I discovered that quad originally referred to the four sides of a square. Thus, a squared variable is quadratic.

I used the quadratic easing curve earlier in Figure 7-4. It's actually half a parabola. Here it is again, for reference purposes, in Figure 7-7. Here's the quadratic ease-in ActionScript function:

```
Math.easeInQuad = function (t, b, c, d) {
    return c^{(t/=d)}t + b;
};
```

Recall that t is time, b is beginning position, c is the total change in position, and d is the duration of the tween. This equation is more complex than the linear tween, but it's the simplest of the equations that implement easing. Basically, I normalize t by dividing it by d. This forces t to fall between 0 and 1. I multiply t by itself to produce quadratic curvature in the values. Then I scale the value from a

FIGURE 7-7 Graph of quadratic easing

![](_page_31_Figure_12.jpeg)

**Robert Penner's** Programming Macromedia Flash (2002)

### ← → C ( ▲ https://easings.net/en

![](_page_32_Figure_5.jpeg)

https://easings.net/en

![](_page_33_Picture_0.jpeg)

### PROGRESS

![](_page_34_Picture_0.jpeg)

100% 1.0

# VALUE

0

![](_page_34_Picture_3.jpeg)

### PROGRESS

![](_page_35_Picture_0.jpeg)

100% 1.0

### VALUE

0

![](_page_35_Picture_3.jpeg)

![](_page_36_Picture_0.jpeg)

![](_page_36_Picture_1.jpeg)

### VALUE

0

![](_page_36_Picture_3.jpeg)

![](_page_37_Picture_0.jpeg)

### ← → C ( ▲ https://easings.net/en

![](_page_38_Figure_5.jpeg)

https://easings.net/en

## ROBERT PFNNFR

### Quadratic Easing

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 $p(t) = t^2$ 

![](_page_39_Picture_5.jpeg)

NOTE: I always wondered why the term quad-ratic (the prefix means "four") is used to describe equations with a degree of two  $(x^2)$ . While writing this chapter, I finally looked it up in the dictionary (RTFD, you might say). I discovered that quad originally referred to the four sides of a square. Thus, a squared variable is quadratic.

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FIGURE 7-7 Graph of quadratic easing

![](_page_39_Figure_12.jpeg)

**Robert Penner's** Programming Macromedia Flash (2002)

![](_page_40_Figure_0.jpeg)

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### https://greensock.com/ease-visualizer

![](_page_40_Picture_3.jpeg)

![](_page_41_Figure_0.jpeg)

![](_page_42_Picture_0.jpeg)

I would go with creating the curves befo

Each type has its own senarate ease-In ease-O

### Once you see "easings", they're everywhere!

# SIMULATION

## **SIMULATION** Use physics or other rules to determine next frame for one or more objects.

![](_page_44_Picture_1.jpeg)

### Craig Reynolds' Boids (1986)

### Robert Hodgin's (Flight 404) Magnetosphere, 2007

![](_page_45_Figure_0.jpeg)

## $\mathbf{T} = \mathbf{0}$

Acceleration is sum of forces acting on particle Add acceleration to velocity Add velocity to position

### T = 1

![](_page_47_Picture_0.jpeg)

## T = 2

![](_page_48_Picture_0.jpeg)

### **T** = **3**

![](_page_49_Picture_0.jpeg)

Initial Velocity

### Initial Position

Constant Acceleration (Gravity)

### $T = 4 \dots$

Acceleration is sum of forces acting on particle Add acceleration to velocity Add velocity to position

![](_page_50_Picture_0.jpeg)

Can be expanded to three dimensions, multiple particles, and attractive and repulsive forces. But the steps between frames will remain basic vector addition.

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http://roberthodgin.com/project/magnetosphere PARTICLE

- Mincut

ATTRACTOR

Sources

TO THE R

DEARTICLE

![](_page_50_Figure_4.jpeg)

PARTICLE

CPARTICLE

```
// Created by Robert Hodgin on 5/14/12.
       Copyright (c) 2012 __MyCompanyName__. All rights reserved.
 6 //
    11
 7
    #include "cinder/app/AppBasic.h"
 9
    #include "cinder/Rand.h"
10
    #include "cinder/Sphere.h"
11
    #include "Particle.h"
12
13
    using namespace ci;
14
15
    Particle::Particle(){}
16
17
    Particle::Particle( const Vec3f &pos, float charge )
18
            : mPos( pos ), mCharge( charge )
19
20 {
                                 = Vec3f::zero();
21
            mVel
                                 = Vec3f::zero();
22
            mAcc
23
                                  = 0.0f;
            mForce
24
25
            mRadius
                                  = 1.0f;
26
            mShellRadius
                          = 12.0f;
27
28
    void Particle::update( const Camera &cam, float dt )
29
                                                                                                                     Add acceleration to velocity
30
                                                                                                                     Add velocity to position
                                  = Sphere( mPos, mRadius * 10.0f );
31
            Sphere s
                                  = cam.worldToScreen( mPos, app::getWindowWidth(), app::getWindowHeight() );
32
            mScreenPos
                          = cam.getScreenRadius( s, app::getWindowWidth(), app::get
33
            mScreenRadius
                                                                                                                                             - menarye * V.JI
                                                                                                         IIICO COT
                                                                                       JJ
34
                                                                                      36
                                  = mCharge * 0.5f + 0.5f;
            mColor
35
36
                                                                                                         mVel += mAcc * dt;
                                                                                      37
37
            mVel += mAcc * dt;
                                                                                                         mPos += mVel * dt;
                                                                                      38
38
            mPos += mVel * dt;
39
            mAcc = Vec3f::zero();
                                                                                                         mAcc = Vec3f::zero();
                                                                                      39
40
41
            mShellRadius = mRadius + fabs( mForce ) * 50000.0f;
                                                                                      40
42
                                                                                                          mchallDadius - mDadius : faha/ mEanas )
                                                                                       11
            mMatrix.setToIdentity();
            mMatrix.translate( mPos );
44
45 }
46
    void Particle::draw()
47
48
            gl::color( Color( mColor, mColor, mColor ) );
49
            gl::drawSphere( mPos, mRadius );
50
```

Acceleration is sum of forces acting on particle

https://github.com/flight404/Eyeo2012

![](_page_51_Picture_3.jpeg)

"The physics of the simple vehicle model is based on forward Euler integration. At each simulation step, behaviorally determined steering forces (as limited by max force) are applied to the vehicle's point mass. This produces an acceleration equal to the steering force divided by the vehicle's mass. That acceleration is added to the old velocity to produce a new velocity, which is then truncated by max speed. Finally, the velocity is added to the old position:

steering\_force = truncate (steering\_direction, max force) acceleration = steering force / mass velocity = truncate (velocity + acceleration, max speed) position = position + velocity

The simple vehicle model maintains its velocity-aligned local space by *incremental adjustment* from the previous time step."

Acceleration is sum of forces acting on particle Add acceleration to velocity Add velocity to position

**Steering Behaviors For Autonomous Characters** Craig W. Reynolds https://www.red3d.com/cwr/steer/gdc99/

![](_page_52_Picture_6.jpeg)

![](_page_53_Picture_0.jpeg)

The Coding Train 🥝 VIEW FULL PLAYLIST

of Code

The Coding Train 🔗

VIEW FULL PLAYLIST

The Coding Train 🛇 VIEW FULL PLAYLIST

The Coding Train 🛇 VIEW FULL PLAYLIST

Code

The Coding Train 🖉 VIEW FULL PLAYLIST

![](_page_53_Picture_6.jpeg)

Nature of Code

The Coding Train 🛇

VIEW FULL PLAYLIST

9: Genetic Algorithms - The 7: Cellular Automata - The Nature 8: Fractals - The Nature of Code of Code Nature of Code

The Coding Train 🛇 VIEW FULL PLAYLIST The Coding Train 🖉 VIEW FULL PLAYLIST

![](_page_53_Picture_10.jpeg)

![](_page_53_Picture_11.jpeg)

https://www.youtube.com/watch?v=qMq-zd6hguc&list=PLRqwX-V7Uu6bR4BcLjHHTopXItSjRA7yG

of Code The Coding Train 📀 VIEW FULL PLAYLIST

![](_page_53_Picture_14.jpeg)

The Coding Train 📀 VIEW FULL PLAYLIST

### Pretty good source in-house

![](_page_54_Picture_0.jpeg)

Integrator class used throughout Ben Fry's first Processing text

A simple, simulation-based easing that can easily be applied to variables to achieve smooth animation.

![](_page_54_Picture_3.jpeg)

![](_page_54_Picture_4.jpeg)

### EXAMPLE

**Integrator** class used throughout Ben Fry's first Processing text

```
if (targeting) {
                                                                  force += attraction * (target - value);
class Integrator {
                                                                accel = force / mass;
 final float DAMPING = 0.5f;
                                                                vel = (vel + accel) * damping;
 final float ATTRACTION = 0.2f;
                                                                value += vel;
                                                                force = 0;
  float value; float vel; float accel; float force;
  float mass = 1;
                                                              void target(float t) {
  float damping = DAMPING;
                                                                targeting = true;
  float attraction = ATTRACTION;
                                                                target = t;
  boolean targeting;
  float target;
                                                              void noTarget() {
 Integrator() { }
                                                                targeting = false;
                                 What this means: An Integrator maintains a current value. That value can
 Integrator(float value) {
    this.value = value;
                                 be set to a new target. With each call to update, it will use a simple
  }
 Integrator(float value, float damping
                                  simulation to move the current value towards the target.
             float attraction) {
   this.value = value;
    this.damping = damping;
    this.attraction = attraction;
```

void set(float v) { value = v;}

void update() {

![](_page_55_Picture_3.jpeg)

![](_page_55_Picture_4.jpeg)

### EXAMPLE

**Integrator** class used throughout Ben Fry's first Processing text

```
Integrator[] interpolators;
//. . .
void setup() {
 //. . .
 interpolators = new Integrator[rowCount];
 for (int row = 0; row < rowCount; row++) {</pre>
    float initialValue = dataTable.getFloat(row, 1);
    interpolators[row] = new Integrator(initialValue, 0.5, 0.01);
void draw() {
 //. . .
```

```
for (int row = 0; row < rowCount; row++) {</pre>
  interpolators[row].update();
```

```
animates to the new value.
```

The processing sketch maintains an array of Integrators, and calls update on each one in the draw loop. Marks are rendered based on the integrators' current value, and when an integrator's target is changed, the mark

![](_page_56_Figure_6.jpeg)

![](_page_56_Picture_7.jpeg)

![](_page_56_Picture_8.jpeg)

### TIMELINES

What time is it NOW?

Based on that, what should I do?

![](_page_59_Figure_1.jpeg)

"Something" could really be anything: a function to call, a variable with a new value, a string label...

![](_page_60_Figure_1.jpeg)

Maintain list of events ordered by increasing timestamp.

Each time through a loop, get the current time.

Get a list of any events with a timestamp < current time.

Handle each event in the list. This could be as simple as a switch case statement with a list of modes.

```
//basic event handler:
switch(event_label) {
    case "END_INTRO":
    //something
    break;
    case "START_CHAPTER_!":
    //something
    break;
    case "END_CHAPTER_1":
    //something
    break;
    //Etc...
}
```

![](_page_60_Picture_7.jpeg)

![](_page_61_Figure_1.jpeg)

Creating a case for each event does not scale well with more than a few events. A better system would have a flexible means of triggering just about anything possible in an environment: calling a function, updating a variable value, starting an easing that updates a variable value, triggering another timeline, etc.

# **BETTER TIMELINE ALGORITHM**

![](_page_62_Figure_1.jpeg)

Greensock - the same library with robust easing tools - has comprehensive timeline features, too:

25	<pre>var x=20, y=20, opacity=.5; //GS can man;</pre>
26	<pre>var obj = {prop: 10}; //GS can manipulate</pre>
27	<pre>var tl = gsap.timeline({repeat: 20, repea</pre>
28	//to hold o
20	

65	<pre>//Add animation events to the timeline</pre>
66	//See https://greensock.com/docs/v3/GS/
67	<pre>tl.to(this, {x: 300, duration: 1}); //a</pre>
68	<pre>tl.to(this, {y: 3*height/4, duration: 3</pre>
69	<pre>tl.to(this, {opacity: 255, duration: 1]</pre>
70	

ipulate variables (in "this" scope) e object fields and pretty much anything else atDelay: 1}); //An empty timeline, events defined in setup

AP/Timeline animate the X global to value 100 over 1 second 2, delay: -.5}); // animate y }); //animate opacity

![](_page_62_Picture_7.jpeg)

![](_page_62_Picture_8.jpeg)